

# Updated Design of TCLD whit reduced jaw length

Collimation Upgrade Specification meeting 18-10-2013

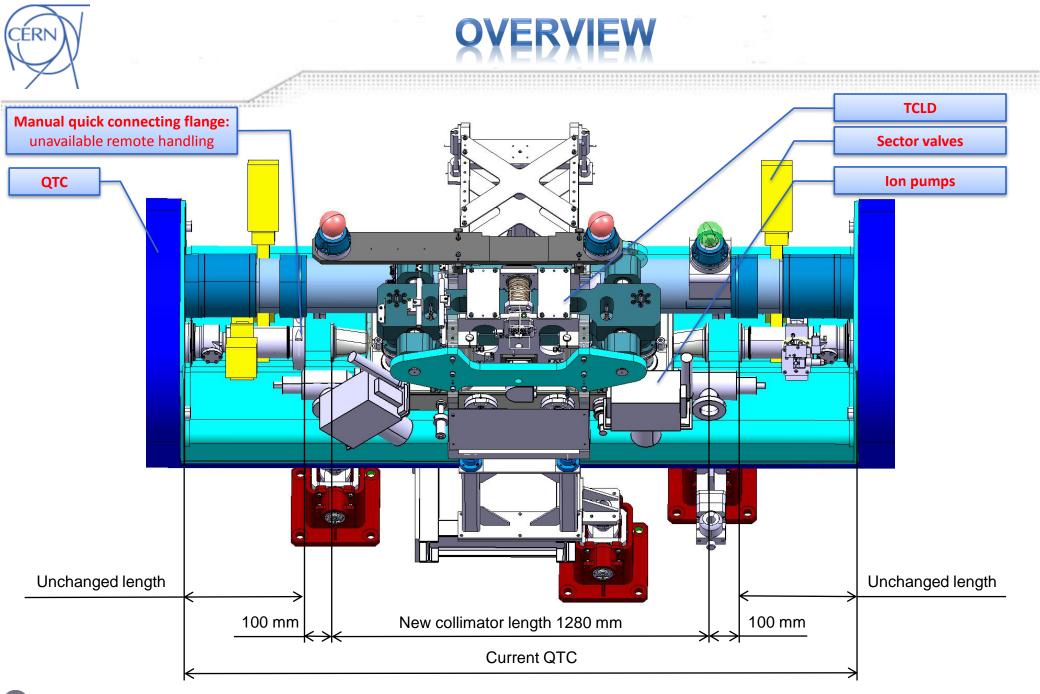
L. GENTINI





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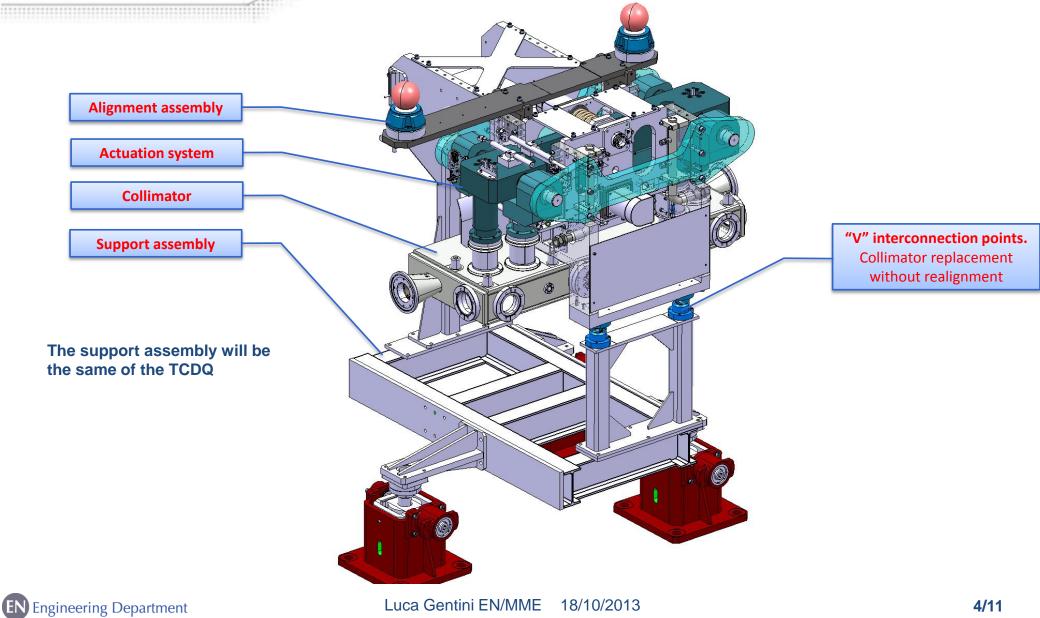


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### COLLIMATOR ASSEMBLY





### ACTUATION SYSTEM

#### Frame

- Partially recovered from existing TCLD actuation system

#### Movement

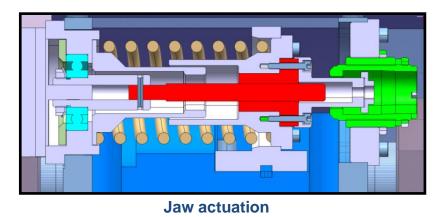
- No jaw tilting
- Stroke: 0 → 25 mm
- One step motor each jaw
- Spring-back: in case of electrical short-cut the jaws must not go in beam direction

#### Instrumentation

- 3x LVDT (1x each jaw, 1x anti-collision)
- 3x switch assemblies (1x each jaw, 1x anti-collision)

#### Alignment

- Adjusting assembly with 2x laser trackers



 To be changed

 To be changed



Recovered

Recovered

**Recovered** 



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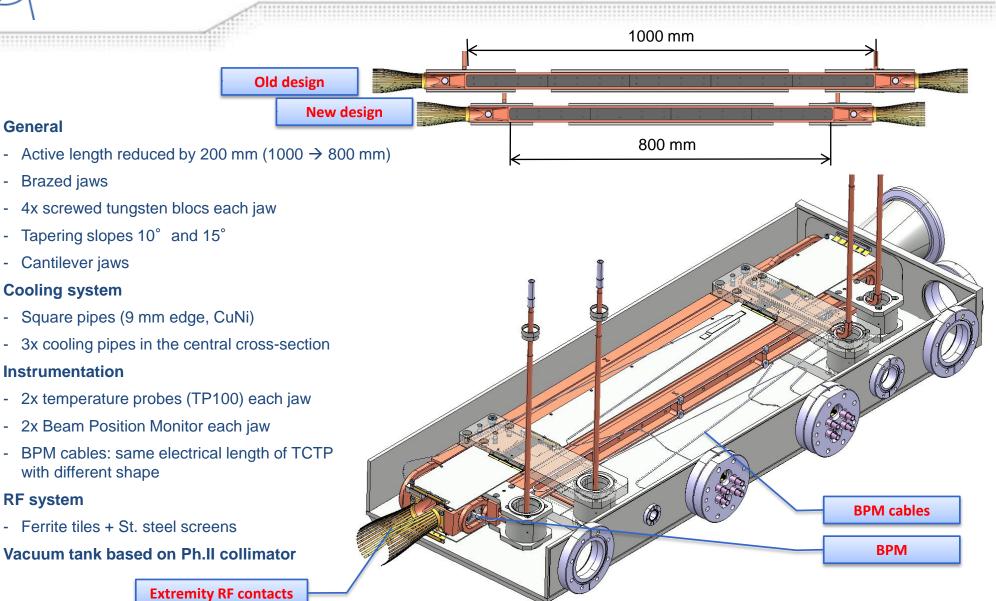
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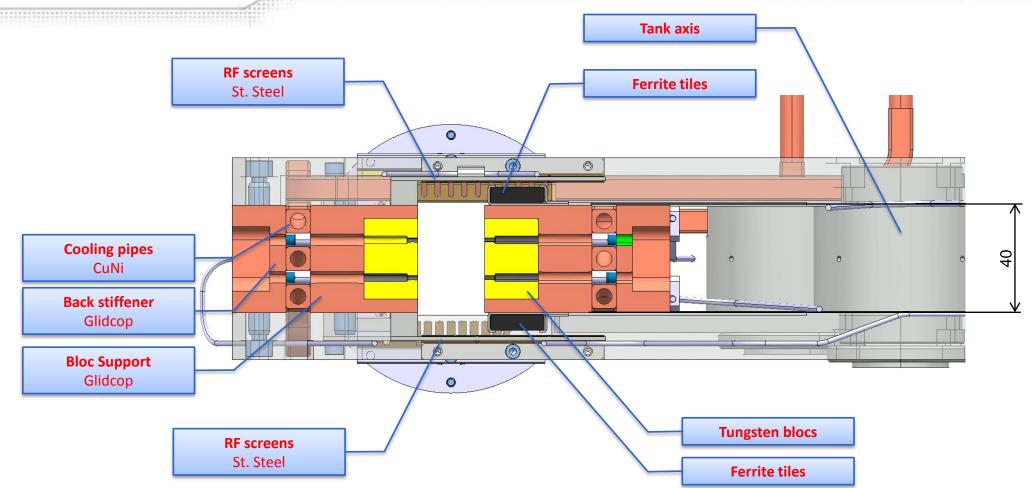
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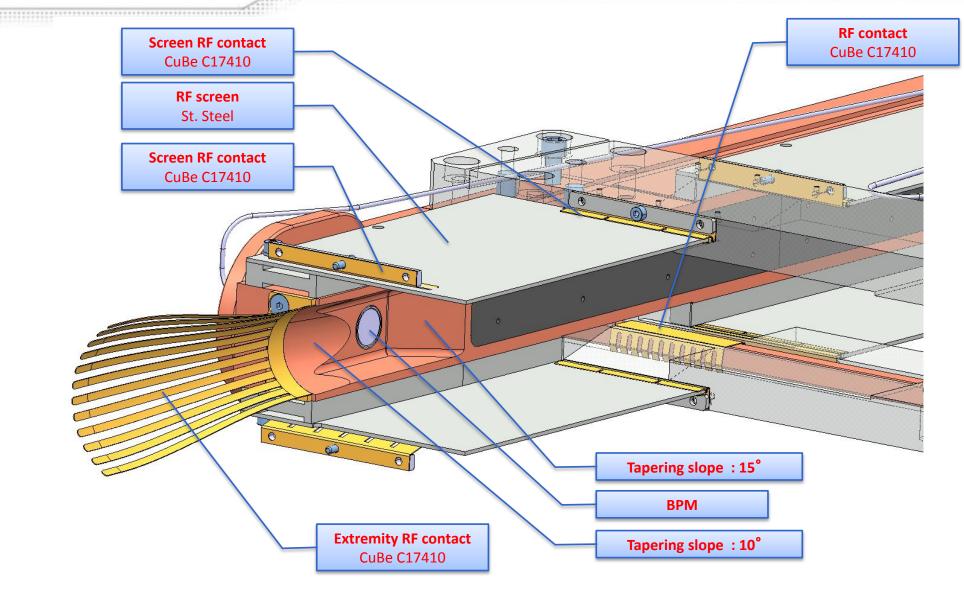
### **JAW RETAILS**





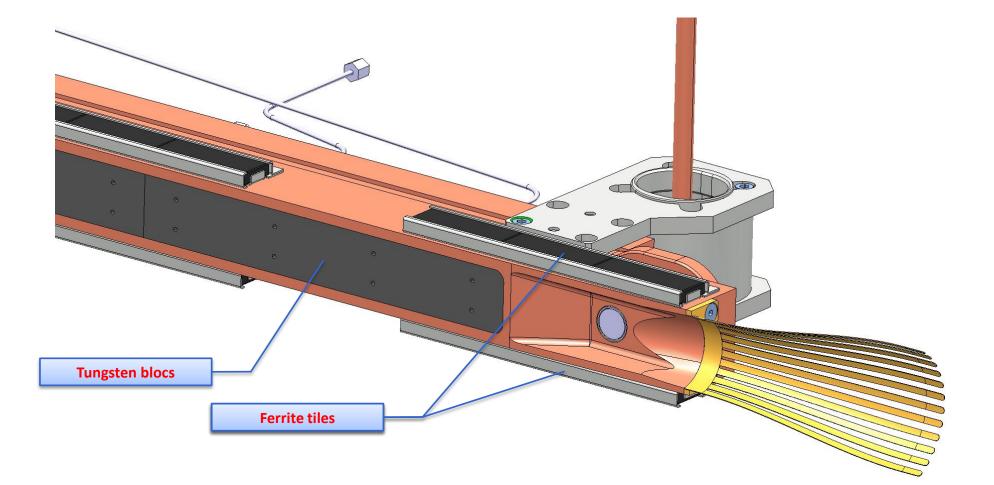


### JAW RETAILS





### **JAW RETAILS**





### TCLD UPDATED DESIGN STATUS

18-10-2013	Study	3D models	Drawings	Controls	Manufacturing
Actuation System	100%	95%	70%	70%	60%
Jaws	80%	70%	30%	0%	0%
Tank	100%	100%	50%	0%	0%
Support	100%	100%	0%	0%	0%
Jacks	70%	70%	70%	70%	70%
Test tools	30%	30%	20%	20%	20%





## Thank you for your attention!



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